

SIGNALS & SYSTEMS (ELEC 2202)

Time Allotted : 2½ hrs

Full Marks : 60

Figures out of the right margin indicate full marks.

***Candidates are required to answer Group A and
any 4 (four) from Group B to E, taking one from each group.***

Candidates are required to give answer in their own words as far as practicable.

Group – A

1. Answer any twelve:

12 × 1 = 12

Choose the correct alternative for the following

- (i) Integration of an impulse signal is
 (a) ramp signal (b) step signal
 (c) parabolic signal (d) gate signal
- (ii) If a signal $f(t)$ has energy E , the energy of the signal $f(t/2)$ is equal to
 (a) E (b) $E/2$ (c) $2E$ (d) $4E$
- (iii) If a periodic signal has an even symmetry, the Fourier series contains
 (a) only sine terms (b) only cosine terms
 (c) both constant and cosine terms (d) both constant and sine terms
- (iv) The odd component of the signal $x(t) = u(t) - u(t - 1)$ with $u(t) =$ unit step function is
 (a) $x_o(t) = \begin{cases} 1 & \text{for } -1 \leq t \leq 2 \\ 0 & ; \text{ elsewhere} \end{cases}$ (b) $x_o(t) = \begin{cases} 0.5 & \text{for } -1 \leq t \leq 1 \\ 0 & ; \text{ elsewhere} \end{cases}$
 (c) $x_o(t) = \begin{cases} 0.5 & \text{for } 0 \leq t \leq 1 \\ -0.5 & ; \text{ elsewhere} \end{cases}$ (d) $x_o(t) = \begin{cases} 0.5 & \text{for } 0 \leq t \leq 1 \\ -0.50 & ; -1 \leq t \leq 0 \end{cases}$
- (v) The inversez – transform for the discrete signal $X(z) = z/(z - \frac{1}{2})$ for R.O.C $:|z| < \frac{1}{2}$ is
 (a) $x(n) = (\frac{1}{2})^n u(n)$ (b) $x(n) = (2)^n u(n)$
 (c) $x(n) = (\frac{1}{2})^n u(-n - 1)$ (d) $x(n) = (2)^n u(-n - 1)$
- (vi) The time response of a second order system gives critically damped characteristics if damping factor is
 (a) 1 (b) 0.707 (c) less than 0.707 (d) less than 1
- (vii) In force-current analogy, mass is analogous to
 (a) resistance (b) inductance
 (c) capacitance (d) conductance

- (viii) The transfer function of a 2nd order system is $G(s) = \frac{100}{s^2 + 12s + 100}$. Its damping factor is
 (a) 0.8 (b) 1 (c) 2 (d) 0.6
- (ix) The state variable analysis can be used to analyse
 (a) linear time-invariant system (b) time-variant system
 (c) nonlinear system (d) all of the above
- (x) A system is described by the differential equation $\ddot{x} + 5\dot{x} + 6x = f(t)$. The 'A' matrix of the system is given by
 (a) $A = \begin{bmatrix} 0 & -1 \\ -6 & -5 \end{bmatrix}$ (b) $A = \begin{bmatrix} 0 & -1 \\ 6 & -5 \end{bmatrix}$
 (c) $A = \begin{bmatrix} 0 & 1 \\ -5 & -6 \end{bmatrix}$ (d) $A = \begin{bmatrix} 0 & 1 \\ -6 & -5 \end{bmatrix}$

Fill in the blanks with the correct word

- (xi) All periodic signals are an example of _____ signal.
- (xii) For the system the settling time is _____.
- (xiii) The z-transform of unit ramp sequence is _____.
- (xiv) In state variable analysis response due to initial condition is also known as _____.
- (xv) A system is said to be linear if it follows _____.

Group - B

2. (a) Examine whether unit step signal is an energy or power signal. [[CO1](Analyze/IOCQ)]
 (b) Sketch the signal $f(t) = r(t + 2) - r(t + 1) - r(t - 1) + r(t - 2)$. [[CO1](Understand/LOCQ)]
 (c) Sketch the even and odd components of a signal $x(t) = e^{at}u(t)$. [[CO1](Understand/LOCQ)]
 (d) Determine the output of the system whose impulse response $h(t) = u(t + 3)$ for an input signal $x(t) = e^{-2t}u(t)$ by graphical convolution. [[CO2](Evaluate/HOCQ)]
3 + 2 + 2 + 5 = 12

3. (a) Determine the exponential Fourier series for the signal $x(t)$ shown in Fig. 1.

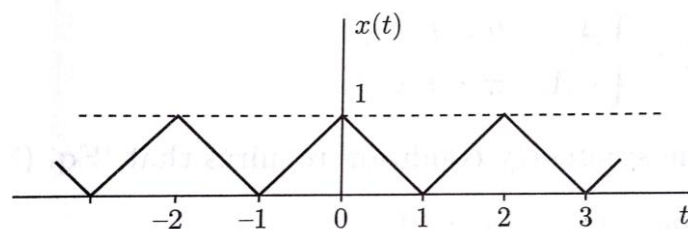


Fig. 1

- (b) Obtain the Fourier transform of the signal $x(t)$ shown in Fig. 2. Also sketch the amplitude and the phase spectra of the signal. [[CO1](Analyze/IOCQ)]

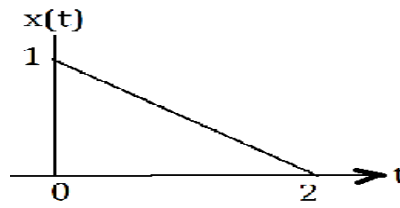


Fig. 2

6 + 6 = 12

Group - C

4. (a) Explain the aliasing phenomenon? How can we prevent aliasing? [[CO3](Remember/LOCQ)]
- (b) Find the z-transform and their ROC for the following signals.
- (i) $x(n) = \left[\left(\frac{2}{5}\right)^n + \left(\frac{1}{3}\right)^n\right]u(n)$ (ii) $g(n) = n(r)^n u(n)$ [[CO3](Analyze/IOCQ)]
- (2 + 2) + (4 + 4) = 12**
5. (a) Find the inverse z-transform of the following functions using partial fraction method.
- (i) $X(z) = \frac{1}{1 - 0.8z^{-1} + 0.15z^{-2}}$, ROC $|z| > 0.5$
- (ii) $X(z) = \frac{z}{z^2 + 6z + 8}$, ROC $|z| > 2$ [[CO3](Analyze/IOCQ)]
- (b) Determine the impulse response of the system whose input $(x(n))$ and output $(y(n))$ relationship is given by the difference equation $y(n] = 6y(n - 1) - 9y(n - 2) + x(n)$. [[CO3](Evaluate/HOCQ)]
- (4 + 4) + 4 = 12**

Group - D

6. (a) State the difference between time variant and time invariant system. [[CO4](Understand/LOCQ)]
- (b) Develop the force equilibrium equations for the mechanical system shown in Fig. 3. Hence, draw the force-voltage and force-current analogous circuit.

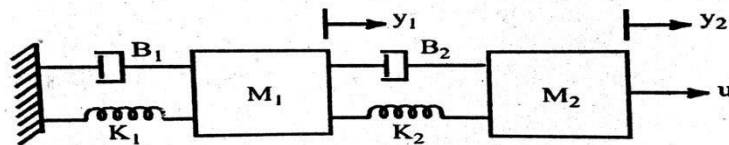


Fig. 3

[[CO4] (Evaluate /HOCQ)]
2 + (2 + 4 + 4) = 12

7. (a) Define 'Rise time' and 'Peak time' of a system. [[CO5](Understand/LOCQ)]
- (b) A system is described by a differential equation $\frac{d^2c}{dt^2} + 10\frac{dc}{dt} + 49c(t) = 49r(t)$, where $c(t)$ is the output and $r(t)$ is the input to the system. Find out the
- (i) transfer function of the system
- (ii) natural frequency of oscillation and damping ratio of the system
- (iii) unit step response of the system and sketch the output
- (iv) peak time and percentage over shoot of the system.

(v) rise time and settling time of the system.

[[C05](Analyze/IOCQ)]

2 + 10 = 12

Group - E

8. (a) Obtain the state variable model of an armature controlled D.C servo motor.

[[C06](Analyze/IOCQ)]

(b) Develop the state variable model of the system whose transfer function is given by

$$G(s) = \frac{s^2 + 5s + 3}{s^5 + 5s^4 + 6s^3 + 7s^2 + 8s + 9}$$

[[C06](Analyze/IOCQ)]

6 + 6 = 12

9. The state variable model of a system is given by,

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 2 \\ 1 \end{bmatrix} u \text{ and } y = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Evaluate the

(i) transfer function of the system.

(ii) state transition matrix

(iii) zero input response if $x_1(0) = 0$ and $x_2(0) = 1$

(iv) response due to unit impulse input.

[[C06](Evaluate/HOCQ)]

(3 + 3 + 2 + 4) = 12

Cognition Level	LOCQ	IOCQ	HOCQ
Percentage distribution	12.5	55.2	32.3

Course Outcome (CO):

After the completion of the course students will be able to

CO1: Understand the concept of signals and analyze the spectral content in periodic and aperiodic signals.

CO2: Understand the impulse response of a system, convolution of two signals and its application to dynamic systems.

CO3: Understand the concept of sampling of a signal; obtain the output of a system using z – transform.

CO4: Describe the mathematical model of physical systems and understand the concept of BIBO stability.

CO5: Possess a basic understanding of the concept of frequency response and time response of dynamic systems and analyze their implications.

CO6: Describe the mathematical model of dynamical systems in state-space form and its time domain solution using the concept of “state transition matrix”.

*LOCQ: Lower Order Cognitive Question; IOCQ: Intermediate Order Cognitive Question; HOCQ: Higher Order Cognitive Question.