B. TECH/ME/7TH SEM/MECH 4142/2023

MATERIALS HANDLING (MECH 4142)

Time Allotted: 2½ hrs Full Marks: 60

Figures out of the right margin indicate full marks.

Candidates are required to answer Group A and any 4 (four) from Group B to E, taking one from each group.

Candidates are required to give answer in their own words as far as practicable.

	Group – A								
1.	Answ	er any twelve:	$12 \times 1 = 12$						
	Choose the correct alternative for the following								
	(i)	One of the disadvantages of MH system is (a) cut down labour cost (c) more chances of accidents	(b) improve efficiency of production(d) additional capital cost.						
	(ii)	Statement 1: It is generally not possible to chan Statement 2: If belt conveyors are to be use (a) true, false (c) false, false	_						
	(iii)	Steel scrap can be lifted best by (a) hook (c) orange peel grab	(b) clamshell grab(d) tongs.						
	(iv)	Rope drum is used in a (a) winch (c) chain pulley block	(b) multi pulley system(d) robot.						
	(v)	Which of the following elements consists (a) Piles and rubber (b) Top cover, carcass and bottom cover (c) Belt splicing and idlers (d) Synthetic rubber and plastics.	of a conveyor belt?						
	(vi)	In the vibrating feeder, material is moved (a) circular motion (c) hopping motion							
	(vii)	Belt conveyors are generally employed for (a) intermittent flow (c) vibration	r of materials (b) continuous flow (d) mixing						

(viii)	Troughed belt conveyors have conveyors of equal belt width.	e carrying capacity than flat belt								
	(a) more (b) less	(c) equal (d) both (b) and (c)								
(ix)	Dynamic loading phenomena is common in (a) belt conveyors (b) chain conveyors (c) screw conveyors (d) pneumatic conveyors.									
(x)	Moving a large load over some (a) truck mounted crane (c) EOT crane	distance in a construction site is best done by (b) crawler type crane (d) level luffing crane.								
	Fill in the blanks with the correct word									
(xi)	To avoid the chance of toppling while lifting a load, out riggers are used in									
(xii)	As an unit load is moved by a Level Luffing Crane, the height of the load from ground									
(xiii)	The hoisting equipment which is used for self-loading and shifting them to different places in a factory is									
(xiv)	Counter balance in fork lift truck lies in									
(xv)	Work envelope of a Cartesian co-ordinate robot is									
	Gr	oup - B								
(a)	Define the term "Materials Hand	dling". Explain the objectives of MH.								
(b)	Briefly mention the selection criteria of MH equipment in a particular Industry according to your choice. [(CO1)(Understand/LOCQ)] $6+6=12$									
(a) (b)	-	ization with suitable examples. [(CO1)(Analyse/LOCQ)] all features of fork lift trucks. [(CO2)(Understand/LOCQ)] $6+6=12$								
	Group - C									
(a)	Specify the various characterist									
(b)	With the help of suitable so features of Trolley type chain co	thematic diagrams, explain the constructional onveyors. $[(CO3)(Understand/LOCQ)]$ $[(CO3)(Understand/LOCQ)]$ $6 + 6 = 12$								
(a) (b)		umatic conveyors? [(CO3)(Analyse/IOCQ)] apacity of a screw conveyor inclined at 10° to the nm nominal screw diameter, and screw pitch								

2.

3.

4.

5.

160mm, running at 100rpm. Given, loading efficiency of the vertical cross sectional area Φ =0.25 and inclination factor C=0.8. [(CO3)(Evaluate/HOCQ)]

6 + 6 = 12

Group - D

6. (a) What is "Wire Rope"? Mention the types and the construction of Wire Rope.

[(CO4)(Analyse/IOCQ)]

(b) What are the advantages and disadvantages of Regular Lay and Parallel Lay Ropes? [(CO4)(Remember/LOCQ)]

6 + 6 = 12

- 7. (a) Describe with a neat sketch the hoisting mechanism of a clamshell grab. What are the types of material it can handle? [(CO4)(Analyse/HOCQ)]
 - (b) Describe with a schematic diagram, working of aLvel Luffing Wharf crane. Why it is called Level Luffing. [(CO4)(Apply/HOCQ)]

6 + 6 = 12

Group - E

8. (a) Briefly mention the types and usages of Belt Feeders and Apron Feeders.

[(CO6)(Analyse/HOCQ)]

(b) Explain Chutes and Trough Gate with line sketches and their applications.

[(CO6)(Remember/IOCQ)]

6 + 6 = 12

9. (a) Define the term "Robot". What are the classifications of Robots?

[(CO5)(Analyse/HOCQ)]

(b) Illustrate briefly robotic handling application in respect of (i) material transfer and (ii) machine loading and unloading. [(CO5)(Remember/LOCQ)]

$$(3+3)+(3+3)=12$$

Cognition Level	LOCQ	IOCQ	HOCQ
Percentage distribution	50	19	31

Course Outcomes (CO):

After completing this course, the students will be able to

- CO1: State the importance of materials handling equipment, its classification and select appropriate material handling equipment.
- CO2: State the constructional features of different trucks and vehicle
- CO3: Describe the constructional features and designs of conveyor systems
- CO4: Explain the working principle of different hoisting equipment and their purpose
- CO5: Implement automation and robotics in materials handling system
- CO6: Distinguish different types of auxiliary handling equipment and apply the knowledge of maintenance and safety in materials

^{*}LOCQ: Lower Order Cognitive Question; IOCQ: Intermediate Order Cognitive Question; HOCQ: Higher Order Cognitive Question.