ECEN 3231

B.TECH/ECE/6TH SEM/ECEN 3231/2021

DIGITAL IMAGE PROCESSING & PATTERN RECOGNITION (ECEN 3231)

Time Allotted : 3 hrs

Figures out of the right margin indicate full marks.

Candidates are required to answer Group A and <u>any 5 (five)</u> from Group B to E, taking <u>at least one</u> from each group.

Candidates are required to give answer in their own words as far as practicable.

Group – A (Multiple Choice Type Questions)

1. Choose the correct alternative for the following:

(i)	The decision boundary classifier is the vectors mi and mj. (a) first quartile (c) perpendicular bised	y between classes wi a of the line segment ctor	nd wj for a minimum joining the correspondi (b) second part (d) circle locus	distance ng mean
(ii)	The number of bits used (a) 8	d to represent 512 shade (b) 9	es of gray is (c) A	(d) B.
(iii)	The D4 distance betwee (a) City Block distance (c) Chess board distance	en points P and Q in an d e	igital image is given by (b) Euclidean distance (d) Potential distance.	
(iv)	If a 10mm × 10mm image with highest resolution of 2 line pair/ mm is digiti then a minimum number of × pixels each of size mm can han it. (a) 20, 20, 0.5 (b) 40, 40, 0.25 (c) 20, 40, 0.25 (d) 40, 20, 0.50.			
(v)	Aliasing can be avoided image. This minimum sa (a) Nyquist (c) Nyon	l by choosing a sampling ampling rate is called the	g rate ≥ 2 * max frequen e rate. (b) Nyman (d) Nyquil.	cy in the
(vi)	A monochromatic digit and the (a) two, spatial, graysca (c) two, spatial, color	al image is sampled in <u>.</u> lle	(b) two, color, graysca (d) three, spatial, grays	vhich are lle scale.

Full Marks: 70

 $10 \times 1 = 10$

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(vii)	The inverse Fourier Transform o function implies no effect a (a) Salt and Pepper (c) Ringing	f a low pass Gaussian Filter is also a Gaussian after using this filter. (b) Averaging (d) Shading.
(viii)	Pattern arrangements for description it is either in string or (a) quantitative, structural (c) qualitative, quantitative	description is in vector form, and for in tree form (b) behavioural, scientific (d) scientific, structural.
(ix)	In learning, a teacher rout pattern in a training set. In <i>system forms</i> clusters of the input	ine provides a category label or cost for each learning <i>there is no explicit teacher, and the</i> patterns

- (a) Supervised, Unsupervised(b) R(c) Unsupervised, Supervised(d) U
 - (b) Reinforced, Supervised
 - (d) Unsupervised, Reinforced.
- (x) In SVM (support vector machine), the support vectors are the data points that lie ______ to the decision surface.
 (a) farthest (b) closest (c) unseen (d) undetected.

Group – B

- (a) A CCD camera chip of dimensions 8*8 mm, and having 2048*2048 elements, is focused on a square, flat area, located 0.4 m away. How many line pairs, per mm will this camera be able to resolve? The camera is equipped with a 32-mm lens.
 - (b) Consider the image segment shown below.
 (i) Let V={0, 1} and compute the lengths of the shortest 4-, 8-, and m-path between p and q. If a particular path does not exist between these two points, explain why. (ii) Repeat for V={1, 2}. Image segment:

1	3	1 (q) 2
2	0	2	0
1	1	2	2
(p) 1	0	2	3

6 + (3 + 3) = 12

3. (a) What is Median value of the 3 x 3 Median Filter (in red) as shown on the given data set? Show steps.

102	123	122	145	156	
154	135	143	142	234	
214	145	160	123	125	Median filter 3 x 3
164	131	163	129	165	
187	234	175	153	104~	→ Data Set

(b) If f(x,y) be a monochromatic gray scale 8 bit image and g(x,y) be its corresponding negative transformation (reverse video effect) of f(x,y), then plot the transform curve between f(x,y) and g(x,y).

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(c) What is histogram equalization? How is it used?

4 + 4 + 4 = 12

Group – C

- 4. (a) What is "dilation" and "erosion"? What are use of these operations? What is the function of a structural element?
 - (b) Explain the morphological operation of "OPENING" and "CLOSING" with example. What are its use?
 - (c) Explain the principle of boundary detection with morphological operators.

6 + 4 + 2 = 12

- 5. (a) Briefly explain what is inter-pixel redundancy, and psycho visual redundancy, and how they are related with compressing an image.
 - (b) An image with 8 gray level is represented by Code 1 with 3 bits. It is also represented with variable length Code 2 as shown below. Determine the redundancy and compression ratio with code2.

/	L				
Gray shades	probability of Occurrence	Code1	L1(rk1)	Code 2	L2(rk2)
r0 = 0	0.19	000	3	11	2
r1 = 1/7	0.25	001	3	01	2
r2 = 2/7	0.21	010	3	10	2
r3 = 3/7	0.16	011	3	001	3
r4 = 4/7	0.08	100	3	0001	4
r5 = 5/7	0.06	101	3	00001	5
r6 = 6/7	0.03	110	3	000001	6
r7 = 1	0.02	111	3	000000	6

6 + 6 = 12

Group – D

- 6. (a) What are the different stages in the design of a classification system? Explain with a diagram.
 - (b) Explain the role of a descriptor with a pattern class. What is the role of classifier?
 - (c) What is supervised pattern recognition? What is a training set? How is a-priori information used?

4 + 3 + 5 = 12

- 7. (a) What is unsupervised learning explain with an example?
 - (b) Two pattern classes w1 and w2, using minimum distance classifiers, have sample mean vectors m1 = $[4.3, 1.3]^T$, and m2 = $[1.5, 0.3]^T$, respectively. Find the decision functions and the decision boundary.

6 + 6 = 12

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Group – E

- 8. (a) What are the three conditions for the minimum distance classifier to be optimum in the Bayes sense?
 - (b) What is the mathematical expression for the simplified Bayes decision function and what approximations are used to reach it?
 - (c) Describe a "Perceptron" model for two training class.

3 + 4 + 5 = 12

- 9. (a) What is the function of a threshold element, and an activation element in a Perceptron model?
 - (b) Write short notes on any two from the following topics.(i) SVM model
 - (ii) Principal component analysis
 - (iii) Parzen windows density estimation
 - (iv) Decision tree based classifiers.

4 + (4 + 4) = 12

Department & Section	Submission Link	
ECE	https://classroom.google.com/w/MzAwODExMjU4NDg2/tc/MzY0NjIxNTQ3Njcx	