B.TECH/AEIE/5TH SEM/AEIE 3111/2020

INTRODUCTION TO MECHATRONICS AEIE 3111

Time Allotted : 3 hrs

Full Marks: 70

Figures out of the right margin indicate full marks.

Candidates are required to answer Group A and <u>any 5 (five)</u> from Group B to E, taking <u>at least one</u> from each group.

Candidates are required to give answer in their own words as far as practicable.

Group – A (Multiple Choice Type Questions)

1.	Choose	ose the correct alternative for the following:				$10 \times 1 = 10$	
	(i)	The sensing principle used by gyros (a) moment of inertia (c) Coriolis force		copes is change in (b) linear acceleration (d) rotation speed leading to Coriolis force.			
	(ii)	The most important characteristics of an (a) High common mode gain (c) High common mode rejection ratio		of an instru tio	rumentation amplifier is (b) High differential mode gain (d) Low common mode gain.		
	(iii)	The output circuit to input circuit in a relay is (a) Mechanically isolated (c) Electrically non-isolated		a relay is	(b) Electrically isolated (d) Mechanically non-isolated.		
	(iv)	The shaft torque in a DC motor is given by the formula $J\ddot{\theta} = K_t i - b\dot{\theta}$ (c) $Ri = V - K_e \dot{\theta} - L \frac{di}{dt}$		ollowing equation (b) $J\ddot{\theta} = K_t i - b\dot{\theta}$ (d) $Ri = \dot{\theta} - L \frac{di}{dt}$			
	(v)	The first step in analog to digital conversion is (a) Encoding (c) Sampling		(b) Quantizing (d) Linearization.			
	(vi)	The actuation principle used by micro-gripper is (a) Thermal expansion of two dissimilar metals (b) Electrostatic force (c) Electrical actuation (d) Mechanical actuation					
	(vii)	The performance of DAC is a measure (a) Resolution (c) Conversion speed		re of	e of (b) Input impedance (d) both (a) and (c).		
	(viii)	Choose the correct pie (a) TiNi	ezoelectric ma (b) Quartz	terial from ((c	the following) Si ₂ N ₃	(d) PolySilicon.	

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- (ix) In a standard block diagram of a control system, the block between the controller and plant is known as
 - (a) Final control element
 - (c) Actuator

(b) Sensor

(d) Both (a) and (c).

(x) Which of the following in not an application area for Digitals Signal Processors
 (a) Filtering
 (b) Spectral Analysis
 (c) Impedance matching
 (d) Synthesis.

Group – B

- 2. (a) What do you understand by thermal resistance? What unit does thermal resistance have? Define thermal resistance for turbulent flow.
 - (b) Derive the overall transfer function if the following system in terms of heat input rate (kcal/s) by the heater and steady state temperature of the in/out flowing fluid (°C).



(2+2+2)+6=12

3. (a) What is used to represent capacitance in a fluid system? Derive the overall transfer function of the following system shown in the figure below.



(b) What are the two assumptions made in case of thermal systems while modelling them? What do you understand by thermal capacitance?

(2+4) + (3+3) = 12

Group – C

- 4. (a) Explain the working principle of a relay. State a few application areas where relays are used.
 - (b) What is the actuation principle of a linear micro motor? List a few points of difference between a DSP and a micro-processor.

(3+3) + (4+2) = 12

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- 5. (a) What do you understand by secondary input/s to a MEMS pressure sensor? State names of a few such inputs.
 - (b) Explain the working principle of a solenoid plunger. State a few application areas where solenoid plungers are used.

(4+2) + (4+2) = 12

Group – D

- 6. (a) State the principle of actuation in case of micro-cantilevers. Which material is used in micro-cantilever for actuation?
 - (b) What is the sensing principle used by MEMS gyroscope? State the names of two different MEMS accelerometers based on construction of the sensing structure.
 (4 + 2) + (3 + 3) = 12

(a) What do you understand by single acting pneumatic cylinders? State few differences between single and double acting pneumatic cylinders.

(b) Explain the actuation principle of a MEMS cantilever beam using quartz as actuating element. What is the sensing principle used by MEMS accelerometers?
 (3 + 3) + (3 + 3) = 12

Group – E

- 8. (a) What are Shape memory alloys? Give a one example of a Shape memory alloy. Where are Shape memory alloys used?
 - (b) State the various programming languages described in the IEC 1131-3 standard for programming a PLC. What do you understand by a scan cycle in a PLC?

(2+2+2) + (3+3) = 12

- 9. (a) Explain with a neat circuit diagram the working of an R-2R type DAC. State the final out voltage expression of a 4-bit R-2R type DAC.
 - (b) Implement the digital NOT logic using PLC ladder diagram. What are the major parts of PLC system, explain using neat block diagram.

(3+3) + (4+2) = 12

Department & Section	Submission link:			
AEIE	https://classroom.google.com/c/MTIyNTUxMjk5MjQ4/a/MjcxMTEyOTU 4MDMy/details			

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