

**DIGITAL SIGNAL PROCESSING  
(ELEC 3231)**

Time Allotted : 3 hrs

Full Marks : 70

*Figures out of the right margin indicate full marks.*

*Candidates are required to answer Group A and  
any 5 (five) from Group B to E, taking at least one from each group.*

*Candidates are required to give answer in their own words as far as practicable.*

**Group - A  
(Multiple Choice Type Questions)**

1. Choose the correct alternative for the following: **10 × 1 = 10**
- (i) The fundamental period ( $N$ ) of a periodic signal  $x(n) = 3 \sin\left(\frac{16\pi n}{57}\right)$  is  
 (a)  $N = 29.5$  (b)  $N = 6$  (c)  $N = 18$  (d)  $N = 57$ .
- (ii) The even component of the signal  $x(n) = u(n)$  is  
 (a)  $x_e(n) = \begin{cases} -0.5, & \text{for } n > 0 \\ 1, & \text{for } n = 0 \\ 0.5, & \text{for } n < 0 \end{cases}$   
 (b)  $x_e(n) = \begin{cases} 0.5, & \text{for } n > 0 \\ 0, & \text{for } n = 0 \\ -0.5, & \text{for } n < 0 \end{cases}$   
 (c)  $x_e(n) = \begin{cases} 0.8, & \text{for } n > 0 \\ 1, & \text{for } n = 0 \\ 0.8, & \text{for } n < 0 \end{cases}$   
 (d)  $x_e(n) = \begin{cases} 0.5, & \text{for } n > 0 \\ 1, & \text{for } n = 0 \\ 0.5, & \text{for } n < 0 \end{cases}$
- (iii) From a given signal  $x(n)$ , a signal  $g(n) = x\left(\frac{2n}{3}\right)$  can be generated using  
 (a) up-sampling and down-sampling  
 (b) down-sampling and up-sampling  
 (c) up-sampling, delay, and down-sampling  
 (d) down-sampling, delay, up-sampling.
- (iv) The length of the output response  $y(n)$  with impulse response  $h(n) = (2, 1, 1, 1)$ ,  $0 \leq n \leq 3$  to the input signal  $x(n) = (1, 2)$ ,  $0 \leq n \leq 1$  is  
 (a) 6 (b) 8 (c) 7 (d) 5.

- (v) The R.O.C of  $z$ -transform for the discrete signal  $x(n) = 3^n u(-n)$  (non-causal signal) is  
 (a) R.O.C:  $|z| < 3$   
 (b) R.O.C:  $|z| > 3$   
 (c) R.O.C: Complete  $z$ -complex plane  
 (d) R.O.C: Inside the unit circle of  $z$ -plane.
- (vi) The impulse response of a discrete causal system is given as  $h(n) = a^n u(n)$ , the system is bounded-input-bounded-output stable if  
 (a) The impulse response is absolutely square summable and  $|a| > 1$ .  
 (b) The impulse response is absolutely square summable and  $|a| < 1$ .  
 (c) The impulse response is absolutely summable and  $|a| > 1$ .  
 (d) The impulse response is absolutely summable and  $|a| < 1$ .
- (vii) If the DFT of four point segment signal  $x(n)$  is  $X(0) = 4$ ,  $X(1) = -j2$ ,  $X(2) = 0$ ,  $X(3) = j2$ , then DFT of the corresponding time reversed signal  $g(n) = x(-n)$  is  
 (a)  $X(0) = 4$ ,  $X(1) = j2$ ,  $X(2) = 0$ ,  $X(3) = -j2$   
 (b)  $X(0) = 4$ ,  $X(1) = j2$ ,  $X(2) = 0$ ,  $X(3) = -j2$   
 (c)  $X(0) = 4$ ,  $X(1) = -j2$ ,  $X(2) = 0$ ,  $X(3) = j2$   
 (d)  $X(0) = 0$ ,  $X(1) = j2$ ,  $X(2) = 4$ ,  $X(3) = -j2$ .
- (viii) A signal  $x(n)$  as a 4-point sequence and  $X(k) = \{9, b, 1, -1 - j2\}$  (for  $k = 0$  to 3) as its 4-point DFT. The DFT point at  $k = 2$ , i.e. the value of 'b' is  
 (a)  $-1 + j2$  (b)  $\sqrt{5}$  (c)  $-2 + j1$  (d)  $1 - j2$
- (ix) Let  $x(n) = \{1, 2, 0, 3\}$  for  $n = 0$  to 3. The circularly shifted signal  $x(n+2)$  is  
 (a)  $\{0, 3, 1, 2\}$  for  $n = 0$  to 3  
 (b)  $\{1, 3, 0, 2\}$  for  $n = 0$  to 3  
 (c)  $\{3, 0, 1, 2\}$  for  $n = 0$  to 3  
 (d)  $\{2, 0, 3, 1\}$  for  $n = 0$  to 3.
- (x) In a linear digital system, if  $P_x$  is the power of the input signal and  $P_y$  is the power output signal, then they are related by  
 (a)  $P_y = 0.9 P_x$  (b)  $P_y = H(e^{j\Omega}) P_x$   
 (c)  $P_y = H^2(e^{j\Omega}) P_x$  (d)  $P_y = |H(e^{j\Omega})|^2 P_x$

**Group - B**

2. (a) (i) Show that  $\sum_{n=-M}^M x(n) = x(0) + 2 \sum_{n=1}^M x(n)$  if  $x(n)$  is even and  $\sum_{n=-M}^M x(n) = 0$  if  $x(n)$  is odd.

(ii) Check the discrete time system  $y(n) = x(nM)$  (i.e. down-sampler is considered as a system) for linearity and time invariance.

- (b) (i) Determine the impulse response of the system  $y(n) = a(0)x(n) + b(1)y(n-1)$ ; where  $y(-1) = 0$ ; and establish the condition for which the system is stable. Is the system causal?

(ii) Realize the following digital filter using direct-form II structure:

$$H(z) = \frac{(0.7157z^2 + 1.4314z + 0.7151)}{(z^2 + 1.349z + 0.514)}$$

$$(2 + 2) + (4 + 4) = 12$$

3. (a) (i) A linear time invariant system with impulse response  $h(n)$  is stable, in the bounded-input bounded-output sense, if and only if the impulse response is absolutely summable, that is if  $\sum_{n=-\infty}^{\infty} |h(n)| < \infty$ .
- (ii) If  $x(n)$  is the input and  $h(n)$  is the impulse response of a linear time-invariant discrete system 'S' then output  $y(n)$  is given by  $y(n) = \sum_{m=-\infty}^{\infty} x(m)h(n-m)$ .
- (b) Find the linear convolution of the sequences  $x(n) = \{1, 2, 3, 2\}$ ; for  $-4 \leq n \leq -1$  and  $h(n) = \{1, 4, -2, 3\}$ ; for  $1 \leq n \leq 4$  as an output of the system (i.e.  $y(n) = x(n) * h(n)$ ) using **numerical computation** (vector-matrix computation).

$$(4 + 3) + 5 = 12$$

### Group - C

4. (a) Find the  $z$ -transform of the signal  $x(n) = \left[ 3\left(\frac{4}{5}\right)^n - \left(\frac{2}{3}\right)^{2n} \right] u(n)$  (causal signal) and its R.O.C.
- (b) An IIR filter (system) is described by the difference equation  $y(n) - y(n-1) - 2y(n-2) = x(n)$ ; with  $x(n) = 6u(n)$ . Find (i) the transfer function  $H(z) = \frac{Y(z)}{X(z)}$  of the system (assuming initial conditions are zero) and hence obtain the poles and zeros (ii) the forced, natural response, total response, transient response and steady-state response of the system considering the following initial conditions  $y(-1) = -1$ ,  $y(-2) = 4$ .

$$5 + 7 = 12$$

5. (a) Find the inverse  $z$ -transform of  $X(z) = \frac{z}{(z-1/2)(z-\frac{1}{3})}$ .

- (b) Transform  $H(s) = \frac{s+1}{(s^2+5s+6)}$  into a digital filter ( $H(z)$ ) using the bilinear transformation. Choose sampling period  $T = 1 \text{ sec}$ . Express the system as a difference equation suitable for computer processing.

$$6 + 6 = 12$$

### Group - D

6. (a) Define the *DFT* of a finite sequence and state the fundamental assumptions that are essential to derive the *DFT* expressions.
- (b) Given a sequence  $x(n) = \{1, 2, 3, 4\}$  for  $0 \leq n \leq 3$ , evaluate its *DFT* coefficients  $X(k)$ , and then compute the amplitude spectrum, Phase spectrum and power spectrum for  $X(3)$  only. Highlight the significance of *DFT* coefficients in context with the signal  $x(n)$ .
7. (a) Show that *DFT* of  $\{x(n)\}$  with  $N$ -data points can be computed efficiently as the sum of *DFT* of a signal  $a(n) = \left\{ x(n) + x\left(n + \frac{N}{2}\right) \right\}$  with  $\frac{N}{2}$  data points and *DFT* of a signal  $b(n) = \left\{ x(n) - x\left(n + \frac{N}{2}\right) \right\}$  with  $\frac{N}{2}$  data points.
- (b) Given the *DFT* sequence  $X(k) = \{10, -2 + j2, -2, -2 - j2\}$  for  $0 \leq k \leq 3$ , evaluate its inverse *DFT*  $x(n)$  using decimation-in-frequency *FFT*.

$$4 + 8 = 12$$

$$6 + 6 = 12$$

### Group - E

8. (a) Discuss briefly the frequency response of a linear digital system  $H(z)$  when the system is excited with a causal sinusoidal input signal  $x(n) = A \sin(\Omega n) u(n)$ . Derive the steady-state output response of the system as  $y(n) = A |H(\Omega)| \sin(n\Omega + \angle H(\Omega))$ .
- (b) What is an all-pass filter? Explain. What form does the transfer function of such filter have? Show the poles and zeros distribution in  $z$ -plane. Comments on the stability of the system.
9. (a) With a suitable example, state and explain the design specification of a "lowpass-filter".
- (b) Give a brief outline how one can design low-pass *FIR* filter using "Hamming window" technique. Explain each step clearly.

$$6 + 6 = 12$$

$$4 + 8 = 12$$